

Generalized integral guiding functions and periodic solutions for inclusions with causal multioperators

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Abstract

In the present paper the method of generalized integral guiding functions is applied to study the periodic problem for a differential inclusion with a causal multioperator.

Key words: differential inclusion; causal multivalued map; periodic solution; guiding function; integral guiding function

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1 Introduction

The study of systems governed by differential and functional equations with causal operators, which is due to Tonelli [29] and Tychonov [28], attracts the attention of many researchers. The term causal arises from the engineering and the notion of a causal operator turns out to be a powerful tool for unifying problems in ordinary differential equations, integro-differential equations, functional differential equations with finite or infinite delay, Volterra integral equations, neutral functional equations et al. (see monograph [2]). Various problems for functional differential equations with causal operators were considered in recent

papers [4, 5, 8, 23, 26]. In particular, boundary and periodic problems were studied in [5] and [23]. In the present paper we apply the method of generalized integral guiding functions to the investigation of the periodic problem for a differential inclusion with a multivalued causal operator.

The main ideas of the method of guiding functions were formulated by Krasnoselskii and Perov in the fifties (see [18, 19]). Being geometrically clear, this method was originally applied to the study of periodic and bounded solutions of ordinary differential equations (see, e.g., [20, 24, 25]). Thereafter the method was extended to differential inclusions (see, e.g., [1, 7]), functional differential equations and inclusions (see, e.g., [6, 10, 13, 14, 16]) and other objects. The sphere of applications was extended to the study of qualitative behavior and bifurcations of solutions (see, e.g. [15, 21, 22]) and asymptotics of solutions (see, e.g., [11, 12, 17]). These and other aspects of the method of guiding functions and its applications, as well as the additional bibliography, may be found in the recent monograph [27].

The paper is organized in the following way. After preliminaries (Section 2), we give the notion of a multivalued causal operator (Section 3.1) and formulate the periodic problem for a differential inclusion with a causal multioperator (Section 3.2). Our main existence result (Theorem 2) is presented for the case when the right-hand side of the inclusion is convex-valued and closed.

2 Preliminaries

In what follows we will use some known notions and notation from the theory of multivalued maps (multimaps) (see, e.g., [1, 3, 7, 9]). Recall some of them.

Let (X, d_X) and (Y, d_Y) be metric spaces. By the symbols $P(Y)$ and $K(Y)$ we denote the collections of all nonempty and, respectively, nonempty and compact subsets of the space Y . If Y is a normed space, $Cv(K)$ and $Kv(Y)$ denote the collections of all nonempty convex closed [and, respectively, compact] subsets of Y .

Definition 1 *A multimap $F : X \rightarrow P(Y)$ is called upper semicontinuous (u.s.c.) at a point $x \in X$ if for each open set $V \subset Y$ such that $F(x) \subset V$ there exists $\delta > 0$ such that $d_X(x, x') < \delta$ implies $F(x') \subset V$. A multimap $F : X \rightarrow P(Y)$ is called u.s.c. if it is u.s.c. at each point $x \in X$.*

Definition 2 *A multimap $F : X \rightarrow P(Y)$ is called lower semicontinuous (l.s.c.) at a point $x \in X$, if for each open set $V \subset Y$ such that $F(x) \cap V \neq \emptyset$ there exists $\delta > 0$ such that $d_X(x, x') < \delta$ implies $F(x') \cap V \neq \emptyset$. A multimap $F : X \rightarrow P(Y)$ is called l.s.c. if it is l.s.c. at each point $x \in X$.*

Definition 3 *A multimap $F : X \rightarrow P(Y)$ is called continuous if it is both u.s.c. and l.s.c.*

Definition 4 *A multimap $F : X \rightarrow P(Y)$ is called closed if its graph*

$$\Gamma_F = \{(x, y) \mid (x, y) \in X \times Y, \quad y \in F(x)\}$$

is a closed subset of the space $X \times Y$.

Definition 5 A multimap $F : X \rightarrow P(Y)$ is called compact if its range $F(X)$ is relatively compact in Y .

Remark 1 If multimap $F : X \rightarrow P(Y)$ is closed and compact, it is u.s.c.

Let I be a closed subset of \mathbb{R} endowed with the Lebesgue measure.

Definition 6 A multifunction $F : I \rightarrow K(Y)$ is called measurable if, for each open subset $W \subset Y$, its pre-image

$$F^{-1}(W) = \{t \in I : F(t) \subset W\}$$

is a measurable subset of I .

Remark 2 Each measurable multifunction $F : I \rightarrow K(Y)$ has a measurable selection, i.e., there exists such measurable function $f : I \rightarrow Y$, that $f(t) \in F(t)$ for a.e. $t \in I$.

In the sequel we will use some standard properties of the topological degree theory of single-valued and multivalued vector fields (see, e.g., [3, 7, 9, 18]).

3 Periodic problem for inclusions with causal multioperators

3.1 Causal multioperators

Let $T > 0$ and $\sigma \geq 0$ be given numbers. By the symbols $C([kT - \sigma, (k+1)T]; \mathbb{R}^n)$ and $L^1((kT, (k+1)T); \mathbb{R}^n)$, where $k \in \mathbb{Z}$, we will denote the corresponding spaces of continuous and integrable functions with usual norms.

For any subset $\mathcal{N} \subset L^1((kT, (k+1)T); \mathbb{R}^n)$ and $\tau \in (kT, (k+1)T)$ we define the restriction of \mathcal{N} on (kT, τ) as

$$\mathcal{N} |_{(kT, \tau)} = \{f |_{(kT, \tau)} : f \in \mathcal{N}\}.$$

Definition 7 We will say that \mathcal{Q} is a causal multioperator if for each $k \in \mathbb{Z}$ a multimap

$$\mathcal{Q} : C([kT - \sigma, (k+1)T]; \mathbb{R}^n) \multimap L^1((kT, (k+1)T); \mathbb{R}^n)$$

is defined in such a way that for each $\tau \in (kT, (k+1)T)$ and for all

$$u(\cdot), v(\cdot) \in C([kT - \sigma, (k+1)T]; \mathbb{R}^n)$$

the condition $u |_{[kT - \sigma, \tau]} = v |_{[kT - \sigma, \tau]}$ implies $\mathcal{Q}(u) |_{(kT, \tau)} = \mathcal{Q}(v) |_{(kT, \tau)}$.

Let us consider some examples of causal multioperators. Denote by \mathcal{C} the Banach space $C([-\sigma, 0]; \mathbb{R}^n)$.

Example 1 Suppose that a multimap $F : \mathbb{R} \times \mathcal{C} \rightarrow Kv(\mathbb{R}^n)$ satisfies the following conditions:

(F1) the multifunction $F(\cdot, c) : \mathbb{R} \rightarrow Kv(\mathbb{R}^n)$ admits a measurable selection for every $c \in \mathcal{C}$;

(F2) the multimap $F(t, \cdot) : \mathcal{C} \rightarrow Kv(\mathbb{R}^n)$ is u.s.c. for a.e. $t \in \mathbb{R}$;

(F3) for every $r > 0$ there exists a locally integrable nonnegative function $\eta_r(\cdot) \in L^1_{loc}(\mathbb{R})$ such that

$$\|F(t, c)\| := \sup\{\|y\| : y \in F(t, c)\} \leq \eta_r(t) \quad \text{a.e. } t \in \mathbb{R},$$

for all $c \in \mathcal{C}$, $\|c\| \leq r$.

It is known (see, e.g., [3, 9]) that under conditions (F1) – (F3) for each $k \in \mathbb{Z}$, the superposition multioperator

$$\mathcal{P}_F : C([kT - \sigma, (k+1)T]; \mathbb{R}^n) \multimap L^1((kT, (k+1)T); \mathbb{R}^n),$$

$$\mathcal{P}_F(u) = \left\{ f \in L^1((kT, (k+1)T); \mathbb{R}^n) : f(t) \in F(t, u_t) \quad \text{a.e. } t \in (kT, (k+1)T) \right\} \quad (1)$$

is well defined. Here $u_t \in \mathcal{C}$ is defined as $u_t(\theta) = u(t + \theta)$, $\theta \in [-\sigma, 0]$. It is easy to see that the multioperator \mathcal{P}_F is causal.

Remark 3 We will say that a multimap $F : \mathbb{R} \times \mathcal{C} \rightarrow K(\mathbb{R}^n)$ obeying (F1)-(F2) satisfies the upper Carathéodory conditions. If (F2) may be replaced with

(F2') the multimap $F(t, \cdot) : \mathcal{C} \rightarrow K(\mathbb{R}^n)$ is continuous for a.e. $t \in \mathbb{R}$

we say that F satisfies the Carathéodory conditions.

Example 2 Let $F : \mathbb{R} \times \mathcal{C} \rightarrow Kv(\mathbb{R}^n)$ be a multimap satisfying conditions (F1) – (F3) of Example 1. Suppose that $\{K(t, s) : -\infty < s \leq t < +\infty\}$ is a continuous (with respect to the norm) family of linear operators in \mathbb{R}^n and $m \in L^1_{loc}(\mathbb{R}; \mathbb{R}^n)$ is a given locally integrable function. Consider, for each $k \in \mathbb{Z}$, the Volterra type integral multioperator $\mathcal{G} : C([kT - \sigma, (k+1)T]; \mathbb{R}^n) \multimap L^1((kT, (k+1)T); \mathbb{R}^n)$ defined as

$$\mathcal{G}(u)(t) = m(t) + \int_{kT}^t K(t, s)F(s, u_s)ds,$$

i.e.,

$$\mathcal{G}(u) = \left\{ y \in L^1((kT, (k+1)T); \mathbb{R}^n) : y(t) = m(t) + \int_{kT}^t K(t, s)f(s)ds : f \in \mathcal{P}_F(u) \right\}. \quad (2)$$

It is also obvious that the multioperator \mathcal{G} is causal.

Example 3 Suppose that a multimap $F : \mathbb{R} \times \mathcal{C} \rightarrow K(\mathbb{R}^n)$ satisfies the following condition of almost lower semicontinuity:

(F_L) there exists a sequence of disjoint closed sets $\{J_n\}$, $J_n \subseteq \mathbb{R}$ $n = 1, 2, \dots$ such that: (i) $\text{meas}(\mathbb{R} \setminus \bigcup_n J_n) = 0$; (ii) the restriction of F on each set $J_n \times \mathcal{C}$ is l.s.c.

Then (see, e.g., [3, 9]) under conditions (F_L), ($F3$), for each $k \in \mathbb{Z}$, the superposition multioperator

$$\mathcal{P}_F : C([kT - \sigma, (k+1)T]; \mathbb{R}^n) \multimap L^1((kT, (k+1)T); \mathbb{R}^n)$$

is also well-defined and causal.

3.2 Periodic problem

Denote by C_T the space of continuous T -periodic functions $x : \mathbb{R} \rightarrow \mathbb{R}^n$ with the norm $\|x\|_C = \sup_{t \in [0, T]} \|x(t)\|$. By $\|x\|_2$ we denote the norm of function x in the space L^2 ,

$$\|x\|_2 = \left(\int_0^T \|x(s)\|^2 ds \right)^{\frac{1}{2}}.$$

To define the notion of a periodic causal multioperator, introduce, for $k \in \mathbb{Z}$, the following shift operator $j_k : L^1((kT, (k+1)T); \mathbb{R}^n) \rightarrow L^1((0, T); \mathbb{R}^n)$:

$$j_k(f)(t) = f(t + kT).$$

Definition 8 A causal multioperator \mathcal{Q} will be called T -periodic if, for each $x \in C_T$ and $k \in \mathbb{Z}$,

$$j_k(\mathcal{Q}(x|_{[kT-\tau, (k+1)T]})) = \mathcal{Q}(x|_{[-\tau, T]}).$$

It is clear that, to provide the periodicity of the causal multioperators in the above examples, it is sufficient to assume that the multimaps F are T -periodic in the first argument:

$$F(t + T, c) = F(t, c)$$

for all $(t, c) \in \mathbb{R} \times \mathcal{C}$ and in Example 2, additionally, that function $m(t)$ and family $K(t, s)$ are also T -periodic:

$$m(t + T) = m(t), \quad \forall t \in \mathbb{R};$$

$$K(t + T, s + T) = K(t, s), \quad \forall -\infty < s \leq t < +\infty.$$

It is clear that the condition of periodicity of the causal multioperator allows to consider it only on the space $C([-\tau, T]; \mathbb{R}^n)$.

Given a T -periodic causal multioperator \mathcal{Q} , we will consider the existence of solutions to the following problem:

$$x' \in \mathcal{Q}(x), \tag{3}$$

where $x \in C_T$ is an absolutely continuous function.

Denote by L_T^1 the space of integrable T -periodic functions $f : \mathbb{R} \rightarrow \mathbb{R}^n$.

In this section we will assume that the T -periodic causal multioperator $\mathcal{Q} : C_T \rightarrow Cv(L_T^1)$ satisfies the following conditions:

(Q1) for each bounded linear operator $A : L_T^1 \rightarrow E$, where E is a Banach space, the composition $A \circ \mathcal{Q} : C_T \rightarrow Cv(E)$ is closed;

(Q2) there exists a non-negative T -periodic integrable function $\alpha(t)$ such that

$$\|\mathcal{Q}(x)(t)\| \leq \alpha(t)(1 + \|x(t)\|) \text{ for a.e. } t \in \mathbb{R}$$

for each $x \in C_T$.

To provide condition (Q1) in Examples 1 and 2, it is sufficient to assume, besides the above mentioned periodicity conditions, that the multimap F satisfies conditions (F1) – (F3) (see, e.g. [1], Theorem 1.5.30) and to fulfil condition (Q2), we can suppose, in Example 1, the following sublinear growth condition: for each $x \in C_T$ we have, for some non-negative integrable function $\beta(t)$:

$$\|F(t, x_t)\| \leq \beta(t)(1 + \|x(t)\|) \text{ a.e. } t \in [0, T], \quad (4)$$

and, in Example 2, the global boundedness condition

$$\|F(t, c)\| \leq \gamma(t) \quad (5)$$

for some non-negative integrable function $\gamma(t)$.

To study periodic problem (3) we will need a coincidence point result for a multivalued perturbation of a linear Fredholm operator. Let us give necessary definitions.

Let E_1, E_2 be Banach spaces, $U \subset E_1$ an open bounded set; $l : \text{Dom } l \subseteq E_1 \rightarrow E_2$ a linear Fredholm operator of zero index such that $\text{Im } l \subset E_2$ is closed.

Consider continuous linear projection operators $p : E_1 \rightarrow E_1$ and $q : E_2 \rightarrow E_2$ such that $\text{Im } p = \text{Ker } l$, $\text{Im } l = \text{Ker } q$. By the symbol l_p denote the restriction of the operator l to $\text{Dom } l \cap \text{Ker } p$.

Further, let the continuous operator $k_{p,q} : E_2 \rightarrow \text{Dom } l \cap \text{Ker } p$ is defined by the relation $k_{p,q}(y) = l_p^{-1}(y - q(y))$, $y \in E_2$; the canonical projection operator $\pi : E_2 \rightarrow E_2 / \text{Im } l$ has the form $\pi(y) = y + \text{Im } l$, $y \in E_2$; and $\phi : \text{Coker } l \rightarrow \text{Ker } l$ a continuous linear isomorphism.

Let $\mathcal{G} : \bar{U} \rightarrow Kv(E_2)$ be a closed multimap such that

- (a) $\mathcal{G}(U)$ is a bounded subset of E_2 ;
- (b) $k_{p,q} \circ \mathcal{G} : \bar{U} \rightarrow Kv(E_1)$ is compact and u.s.c.

The following assertion holds true (see [3], Lemma 13.1).

Lemma 1 *Suppose that:*

- (i) $l(x) \notin \lambda \mathcal{G}(x)$ for all $\lambda \in (0, 1]$, $x \in \text{Dom } l \cap \partial U$;
- (ii) $0 \notin \pi \mathcal{G}(x)$ for all $x \in \text{Ker } l \cap \partial U$;
- (iii) $\text{deg}_{\text{Ker } l}(\phi \pi \mathcal{G}|_{\overline{U}_{\text{Ker } l}}, \overline{U}_{\text{Ker } l}) \neq 0$, where the symbol $\text{deg}_{\text{Ker } l}$ denotes the topological degree of a multivalued vector field evaluating in the space $\text{Ker } l$, and $\overline{U}_{\text{Ker } l} = \overline{U} \cap \text{Ker } l$.

Then l and \mathcal{G} has a coincidence point in U , i.e., there exists $x \in U$ such that $l(x) \in G(x)$.

Developing notions introduced in [6, 10, 18], let us give the following definition.

Definition 9 A continuously differentiable function $V : \mathbb{R}^n \rightarrow \mathbb{R}$ is called the integral guiding function for inclusion (3) if there exists $N > 0$ such that

$$\int_0^T \langle \nabla V(x(s)), f(s) \rangle ds > 0 \quad \text{for all } f \in \mathcal{Q}(x), \quad (6)$$

for each absolutely continuous function $x \in C_T$ such that $\|x\|_2 \geq N$ and $\|x'(t)\| \leq \|\mathcal{Q}(x)(t)\|$ a.e. $t \in [0, T]$.

From the definition it immediately follows that the integral guiding function V is a non-degenerate potential in the sense that

$$\nabla V(x) \neq 0,$$

for all $x \in \mathbb{R}^n$, $\|x\| \geq K = \frac{N}{\sqrt{T}}$. Therefore, on each closed ball $B_{\tilde{K}} \subset \mathbb{R}^n$ centered at the origin of the radius $\tilde{K} \geq K$, the topological degree of the gradient $\text{deg}(\nabla V; B_{\tilde{K}})$ is well defined and, moreover, it does not depend on the radius \tilde{K} (see, e.g., [18, 20]). This generic value of the degree will be called the index $\text{Ind } V$ of an integral guiding function V .

Definition 10 A non-degenerate potential $V : \mathbb{R}^n \rightarrow \mathbb{R}$ is called the generalized integral guiding function for inclusion (3) if there exists $N > 0$ such that

$$\int_0^T \langle \nabla V(x(s)), f(s) \rangle ds \geq 0 \quad \text{for some } f \in \mathcal{Q}(x), \quad (7)$$

for each absolutely continuous function $x \in C_T$ such that $\|x\|_2 \geq N$ and $\|x'(t)\| \leq \|\mathcal{Q}(x)(t)\|$ a.e. $t \in [0, T]$.

Now we are in position to formulate the main result of this section.

Theorem 1 Let $V : \mathbb{R}^n \rightarrow \mathbb{R}$ be an generalized integral guiding function for problem (3) such that

$$\text{Ind } V \neq 0.$$

Then problem (3) has a solution.

Remark 4 Notice that conditions of the theorem are fulfilled if, for example, the function V is even or satisfies the coercivity condition: $\lim_{\|x\| \rightarrow +\infty} V(x) = \pm\infty$.

Proof Step 1. Let us consider the case of the strict integral guiding function for inclusion (3). Let us justify the solvability of the following operator inclusion

$$lx \in \mathcal{Q}(x), \quad (8)$$

where $l : \text{Dom } l := \{x \in C_T : x \text{ is absolutely continuous}\} \subset C_T \rightarrow L_T^1$ is the linear Fredholm operator of zero index. It is easy to see that $\text{Ker } l = \mathbb{R}^n$, projection $\pi : L_T^1 \rightarrow \mathbb{R}^n$ may be given by the formula $\pi f = \frac{1}{T} \int_0^T f(s) ds$ and the multioperators $\pi\mathcal{Q}$ and $k_{p,q}\mathcal{Q}$ are convex-valued and compact on bounded subsets.

Now, let, for some $\lambda \in (0, 1]$ a function $x \in \text{Dom } l$ is the solution of the inclusion

$$lx \in \lambda\mathcal{Q}(x.)$$

It means that $x(\cdot)$ is an absolutely continuous function such that $x'(t) = \lambda f(t)$ a.e. $t \in [0, T]$, for some $f \in \mathcal{Q}(x)$.

Then

$$\begin{aligned} \int_0^T \langle \nabla V(x(s)), f(s) \rangle ds &= \frac{1}{\lambda} \int_0^T \langle \nabla V(x(s)), x'(s) \rangle ds = \\ &= \frac{1}{\lambda} \int_0^T V'(x(s)) ds = \frac{1}{\lambda} (V(x(T)) - V(x(0))) = 0, \end{aligned}$$

yielding

$$\|x\|_2 < N.$$

From condition (Q2) it follows that $\|x'\|_2 < M'$, where $M' > 0$. But then there exists also $M > 0$ such that

$$\|x\|_C < M.$$

Now, take as U the ball $B_r \subset C_T$ of the radius $r = \max\{M, NT^{-1/2}\}$. Then we have

$$lx \notin \lambda\mathcal{Q}(x)$$

for all $x \in \partial U$.

Take an arbitrary $u \in \partial U \cap \text{Ker } l$. We have $\|u\| \geq NT^{-1/2}$ and considering u as a constant function, from the definition of the strict integral guiding function we obtain

$$\int_0^T \langle \nabla V(u), f(s) \rangle ds > 0$$

for each $f \in \mathcal{Q}(u)$. But

$$\int_0^T \langle \nabla V(u), f(s) \rangle ds = \langle \nabla V(u), \int_0^T f(s) ds \rangle = T \langle \nabla V(u), \pi f \rangle > 0,$$

and, therefore

$$\langle \nabla V(u), y \rangle > 0$$

for each $y \in \pi \mathcal{Q}(u)$.

It means that $0 \notin \pi \mathcal{Q}(u)$ and, moreover, the multifield $\pi \mathcal{Q}(u)$ and the field $\nabla V(u)$ do not admit opposite directions for $u \in \partial U \cap \text{Ker } l$. It means that they are homotopic and, hence,

$$\deg(\pi \mathcal{Q}|_{\overline{U}_{\text{Ker } l}}, \overline{U}_{\text{Ker } l}) = \deg(\nabla V, \overline{U}_{\text{Ker } l}) \neq 0,$$

where $\overline{U}_{\text{Ker } l} = \overline{U} \cap \text{Ker } l$. Therefore, all conditions of Lemma 1 are fulfilled and problem (8), and, hence (3) have a solution.

Step 2. Now we consider the case of the generalized integral guiding function for inclusion (3). Consider a multimap $B : C_T \rightarrow P(L_T^1)$ defined as

$$B(x) = \left\{ \varphi : |\varphi(t)| \leq \alpha(t)(1 + \|x_t\|) \text{ and } \gamma(x) \int_0^T \langle \nabla V(x(s)), \varphi(s) \rangle ds \geq 0 \right\},$$

where the first relation holds true for a.e. $t \in [0, T]$, $\alpha(\cdot)$ is a function from the condition (Q2), and

$$\gamma(x) = \begin{cases} 0, & \text{if } \|x\|_2 \leq N, \\ 1, & \text{if } \|x\|_2 > N. \end{cases}$$

It is easy to verify that B is a closed multimap.

Let us consider a multimap $Q^B : C_T \rightarrow P(L_T^1)$ given as

$$Q^B(x) = Q(x) \cap B(x).$$

Obviously, the multimap Q^B is closed and the condition (7) is satisfied for all $f \in Q^B(x)$.

For the non-degenerate potential V we define a map $Y_V : \mathbb{R}^n \rightarrow \mathbb{R}^n$ as follows

$$Y_V(x) = \begin{cases} \nabla V(x), & \text{if } \|\nabla V(x)\| \leq 1, \\ \frac{\nabla V(x)}{\|\nabla V(x)\|}, & \text{if } \|\nabla V(x)\| > 1. \end{cases}$$

It is easy to see that the map Y is continuous.

For any $\varepsilon_m > 0$ we define a multimap $Q_m : C_T \rightarrow P(L_T^1)$ as following

$$Q_m(x) = Q^B(x) + \varepsilon_m Y_V(x).$$

The multimap Q_m is closed and for each $\varepsilon_m > 0$ the condition (6) is fulfilled. By applying results of Step 1 we can prove the solvability of the following operator inclusion

$$lx \in Q_m(x),$$

for each $\varepsilon_m > 0$. From which follows the existence of a solution for problem (3).

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