

On nonlinear functional parabolic equations with state-dependent delays of Volterra type

László Simon*

L. Eötvös University of Budapest, Hungary

Communicated by Tibor Krisztin

Abstract. We consider second order quasilinear parabolic equations where also the main part contains functional dependence and state-dependent delay on the unknown function. Existence and some qualitative properties of the solutions are shown.

AMS Subject Classifications: 35R10, 35K59, 35K99

Keywords: Functional parabolic equation; State-dependent delay; Nonlinear parabolic equation.

1. Introduction

In the present paper we shall consider weak solutions of initial-boundary value problems for the equation

$$\begin{aligned} D_t u - \sum_{i=1}^n D_i [a_i(t, x, u, Du; u([\gamma_0(u)](t, x), x))] \\ + a_0^0(t, x, u, Du; u([\gamma_0(u)](t, x), x)) + a_0^1(t, x, u, Du; u([\gamma_1(u)](t, x), x)) \\ + a_0^2(t, x, u, Du; Du([\gamma_2(u)](t, x), x)) = f \end{aligned} \quad (1.1)$$

where the functions

$$a_i, a_i^j : Q_T \times \mathbb{R}^{n+1} \times L^2(Q_T) \rightarrow \mathbb{R}$$

satisfy modified conditions of [9] and $\gamma_j : L^2(Q_T) \rightarrow C(\overline{Q_T})$ are continuous (nonlinear) operators such that $[\gamma_j(u)](\cdot, x)$ is absolutely continuous for a.e. fixed x ,

$$0 \leq [\gamma_j(u)](t, x) \leq t, \quad \frac{\partial}{\partial t} [\gamma_j(u)](t, x) \geq c_0$$

E-mail address: simonl@ludens.elte.hu (L. Simon)

*This work was supported by the Hungarian National Foundation for Scientific Research under grant OTKA K 81403.

with some constant $c_0 > 0$.

This work was motivated by works where nonlinear parabolic functional differential equations were considered which arise in certain applications. (See references in [8].) In [8] and [9] existence theorems and some qualitative properties were proved on solutions to initial value problems for the functional equations (connected with the above applications)

$$D_t u - \sum_{i=1}^n D_i [a_i(t, x, u(t, x), Du(t, x); u)] + a_0(t, x, u(t, x), Du(t, x); u) = f. \quad (1.2)$$

In the present paper we consider (1.1) as a particular case of (1.2) and apply the results of [9] to the equation (1.1).

Differential equations and systems with state-dependent delay in one variable were considered thoroughly e.g. in [3] - [5] (see also the references there).

In Section 2 the existence of weak solutions will be proved and in Section 3 we shall formulate conditions which imply boundedness of solutions, further, stabilization of solutions will be shown as $t \rightarrow \infty$.

2. Existence of solutions

Denote by $\Omega \subset \mathbb{R}^n$ a bounded domain having the uniform C^1 regularity property (see [1]), $Q_T = (0, T) \times \Omega$ and $p \geq 2$ be a real number. Let $V \subset W^{1,p}(\Omega)$ be a closed linear subspace of the usual Sobolev space $W^{1,p}(\Omega)$ (of real valued functions) containing $W_0^{1,p}(\Omega)$ (the closure of $C_0^\infty(\Omega)$). Denote by $L^p(0, T; V)$ the Banach space of the set of measurable functions $u : (0, T) \rightarrow V$ with the norm

$$\| u \|_{L^p(0,T;V)}^p = \int_0^T \| u(t) \|_V^p dt.$$

The dual space of $L^p(0, T; V)$ is $L^q(0, T; V^*)$ where $1/p + 1/q = 1$ and V^* is the dual space of V (see, e.g., [11]).

First we formulate a slight modification of Theorem 1 in [9] which can be proved in the same way.

Assume that functions \tilde{a}_i satisfy the following conditions.

(A₁). The functions $\tilde{a}_i : Q_T \times \mathbb{R}^{n+1} \times L^p(0, T; V) \rightarrow \mathbb{R}$ satisfy the Carathéodory conditions for arbitrary fixed $u \in L^p(0, T; V)$ ($i = 0, 1, \dots, n$).

(A₂). There exist bounded (nonlinear) operators $g_1 : L^2(Q_T) \rightarrow \mathbb{R}^+$ and $k_1 : L^2(Q_T) \rightarrow L^q(\Omega)$ such that

$$|\tilde{a}_i(t, x, \zeta_0, \zeta; u)| \leq g_1(u)[|\zeta_0|^{p-1} + |\zeta|^{p-1}] + [k_1(u)](x)$$

for a.e. $(t, x) \in Q_T$, each $(\zeta_0, \zeta) \in \mathbb{R}^{n+1}$ and $u \in L^p(0, T; V)$.

$$(A_3). \quad \sum_{i=1}^n [\tilde{a}_i(t, x, \zeta_0, \zeta; u) - \tilde{a}_i(t, x, \zeta_0, \zeta^*; u)](\zeta_i - \zeta_i^*) \geq [g_2(u)](t)|\zeta - \zeta^*|^p \quad (2.1)$$

where

$$[g_2(u)](t) \geq c^* [1 + \|u\|_{L^p(0,t;V)}]^{-\sigma^*}, \quad t \in [0, T] \quad (2.2)$$

c^* is some positive constant, $0 \leq \sigma^* < p - 1$.

(A₄). $\sum_{i=0}^n \tilde{a}_i(t, x, \zeta_0, \zeta; u) \zeta_i \geq [g_2(u)](t)[|\zeta_0|^p + |\zeta|^p] - [k_2(u)](t, x)$
 where $k_2(u) \in L^1(Q_T)$ satisfies with some positive constant $\sigma < p - \sigma^*$

$$\|k_2(u)\|_{L^1(Q_T)} \leq \text{const} [1 + \|u\|_{L^p(0,t;V)}]^\sigma, \quad t \in [0, T].$$

(A₅). If $(u_k) \rightarrow u$ weakly in $L^p(0, T; V)$, $(D_t u_k) \rightarrow D_t u$ weakly in $L^q(0, T; V^*)$, $(\zeta_0^k) \rightarrow \zeta_0$ in \mathbb{R} and $(\zeta^k) \rightarrow \zeta$ in \mathbb{R}^n then for a.e. $(t, x) \in Q_T$

$$\lim_{k \rightarrow \infty} \tilde{a}_i(t, x, \zeta_0^k, \zeta^k; u_k) = \tilde{a}_i(t, x, \zeta_0, \zeta; u), \quad i = 0, 1, \dots, n,$$

for a subsequence, in the case $i = 0$ assuming that $(D_l u_k) \rightarrow D_l u$ in $L^2(Q_T)$ ($l = 1, \dots, n$) holds, too.

Remark 2.1. Assumption (A₅) is weaker than the corresponding assumption in [9], assumptions (A₁) - (A₄) are the same.

Definition 2.1. Assuming (A₁)-(A₅), define operator $\tilde{A} : L^p(0, T; V) \rightarrow L^q(0, T; V^*)$ by

$$[\tilde{A}(u), v] = \int_{Q_T} \left\{ \sum_{i=1}^n \tilde{a}_i(t, x, u, Du; u) D_i v + \tilde{a}_0(t, x, u, Du; u) v \right\} dt dx \quad (2.3)$$

where the brackets $[\cdot, \cdot]$ mean the dualities in spaces $L^q(0, T; V^*)$, $L^p(0, T; V)$.

Since the assumptions (A₁) - (A₄) are the same as in [9], we obtain that operator A is bounded, demicontinuous and coercive. By using the same arguments as in [9], one gets by (A₅) that A is pseudomonotone with respect to $D(L) = \{u \in L^p(0, T; V) : D_t u \in L^q(0, T; V^*), u(0) = 0\}$. According to the theory of monotone type operators (see, e.g. [2], [10]) we have

Theorem 2.1. Assume (A₁) - (A₅). Then for any $f \in L^q(0, T; V^*)$ and $u_0 \in L^2(\Omega)$ there exists $u \in L^p(0, T; V)$ such that $D_t u \in L^q(0, T; V^*)$,

$$D_t u + \tilde{A}(u) = f, \quad u(0) = u_0. \quad (2.4)$$

Now we formulate assumptions on functions a_i, a_0^j in equation (1.1).

(B₁). The functions $a_i, a_0^j : Q_T \times \mathbb{R}^{n+1} \times L^2(Q_T) \rightarrow \mathbb{R}$ satisfy the Carathéodory conditions for arbitrary fixed $v \in L^2(Q_T)$ ($i = 1, \dots, n, j = 0, 1, 2$).

(B₂). There exist bounded (nonlinear) operators $g_1 : L^2(Q_T) \rightarrow \mathbb{R}^+$ and $k_1 : L^2(Q_T) \rightarrow L^q(\Omega)$ such that

$$|a_i(t, x, \zeta_0, \zeta; v)| \leq g_1(v)[|\zeta_0|^{p-1} + |\zeta|^{p-1}] + [k_1(v)](x),$$

$$|a_0^j(t, x, \zeta_0, \zeta; v)| \leq g_1(v)[|\zeta_0|^{p-1} + |\zeta|^{p-1}] + [k_1(v)](x)$$

for a.e. $(t, x) \in Q_T$, each $(\zeta_0, \zeta) \in \mathbb{R}^{n+1}$ and $v \in L^2(Q_T)$.

$$(B_3). \quad \sum_{i=1}^n [a_i(t, x, \zeta_0, \zeta; v) - a_i(t, x, \zeta_0, \zeta^*; v)](\zeta_i - \zeta_i^*) \geq [g_2(v)](t)|\zeta - \zeta^*|^p \quad (2.5)$$

where

$$[g_2(v)](t) \geq c^* [1 + \|v\|_{L^2(Q_t)}]^{-\sigma^*}, \quad t \in [0, T], \quad (2.6)$$

c^* is some positive constant, $0 \leq \sigma^* < p - 1$.

$$(B_4). \quad \sum_{i=0}^n a_i(t, x, \zeta_0, \zeta; v)\zeta_i + a_0^0(t, x, \zeta_0, \zeta; v)\zeta_0 \geq [g_2(v)](t)[|\zeta_0|^p + |\zeta|^p],$$

$$|a_0^j(t, x, \zeta_0, \zeta; v)| \leq [h_2^j(v)](t, x)[1 + |\zeta_0|^{\tilde{p}_j} + |\zeta|^{\tilde{p}_j}], \quad j = 1, 2$$

with $0 \leq \tilde{p}_j < p - 1$,

$$\int_{Q_t} |[h_2^j(v)](\tau, x)|^{q_1^j} d\tau dx \leq \text{const} (1 + \|v\|_{L^2(Q_t)})^\sigma \quad \text{where}$$

$$\sigma < p - \sigma^*, \quad q_1^j = p_1^j / (p_1^j - 1), \quad p_1^j = p / (\tilde{p}_j + 1).$$

(B₅). If $(v_k) \rightarrow v$ in $L^2(Q_T)$, $(\zeta_0^k) \rightarrow \zeta_0$ in \mathbb{R} and $(\zeta^k) \rightarrow \zeta$ in \mathbb{R}^n then for a.e. $(t, x) \in Q_T$, for a suitable subsequence

$$\lim_{k \rightarrow \infty} a_i(t, x, \zeta_0^k, \zeta^k; v_k) = a_i(t, x, \zeta_0, \zeta; v), \quad i = 1, \dots, n,$$

$$\lim_{k \rightarrow \infty} a_0^j(t, x, \zeta_0^k, \zeta^k; v_k) = a_0^j(t, x, \zeta_0, \zeta; v), \quad j = 0, 1, 2.$$

On operators γ_j assume that

(G) $\gamma_j : L^2(Q_T) \rightarrow C(\overline{Q_T})$, ($j = 0, 1, 2$) are continuous (nonlinear) operators such that $[\gamma_j(u)](\cdot, x)$ is absolutely continuous for a.e. fixed $x \in \Omega$,

$$\frac{\partial}{\partial t} [\gamma_j(u)](t, x) \geq c_0, \quad 0 \leq [\gamma_j(u)](t, x) \leq t$$

with some constant $c_0 > 0$ and $\frac{\partial}{\partial t} [\gamma_2(\cdot)] : L^2(Q_T) \rightarrow C(\overline{Q_T})$ is continuous operator.

Example 2.1. Condition (G) is fulfilled e.g. by the operators of the form

$$[\gamma(u)](t, x) = t\beta \left\{ \int_{Q_t} \Gamma(t, \tau, x, \xi) u^2(\tau, \xi) d\tau d\xi \right\}$$

where $\Gamma, \frac{\partial \Gamma}{\partial t}$ are continuous on $\overline{Q_T} \times \overline{Q_T}$, further, $\Gamma, \frac{\partial \Gamma}{\partial t} \geq 0$, $\beta \in C^1(\mathbb{R})$ satisfies $\delta_1 \leq \beta \leq 1$ with some constant $\delta_1 > 0$ and $\beta' \geq 0$.

Definition 2.2. Assuming (B_1) - (B_5) , (G) , define operator $A : L^p(0, T; V) \rightarrow L^q(0, T; V^*)$ by

$$\begin{aligned} [A(u), v] &= \sum_{i=1}^n \int_{Q_T} a_i(t, x, u, Du; u([\gamma_0(u)](t, x), x)) D_i v \, dt dx \\ &+ \sum_{j=0}^1 \int_{Q_T} a_0^j(t, x, u, Du; u([\gamma_j(u)](t, x), x)) v \, dt dx \\ &+ \int_{Q_T} a_0^2(t, x, u, Du; Du([\gamma_2(u)](t, x), x)) v \, dt dx. \end{aligned}$$

Theorem 2.2. Assume (B_1) - (B_5) , (G) . Then for any $f \in L^q(0, T; V^*)$ and $u_0 \in L^2(\Omega)$ there exists $u \in L^p(0, T; V)$ such that $D_t u \in L^q(0, T; V^*)$,

$$D_t u + A(u) = f, \quad u(0) = u_0. \quad (2.7)$$

Proof. Define functions \tilde{a}_i by

$$\begin{aligned} \tilde{a}_i(t, x, \zeta_0, \zeta; u) &= a_i(t, x, \zeta_0, \zeta; u([\gamma_0(u)](t, x), x)), \quad i = 1, \dots, n \\ \tilde{a}_0(t, x, \zeta_0, \zeta; u) &= a_0^0(t, x, \zeta_0, \zeta; u([\gamma_0(u)](t, x), x)) \\ &+ a_0^1(t, x, \zeta_0, \zeta; u([\gamma_1(u)](t, x), x)) \\ &+ a_0^2(t, x, \zeta_0, \zeta; Du([\gamma_2(u)](t, x), x)). \end{aligned}$$

We shall show that these functions \tilde{a}_i satisfy the assumptions (A_1) - (A_5) . Clearly, (A_1) , (A_3) are satisfied by (B_1) , (B_3) . Further, by using the notation $\psi_j(t, x) = [\gamma_j(u)](t, x)$ and (G) ,

$$\begin{aligned} \| u([\gamma_j(u)](t, x), x) \|_{L^2(Q_{\tilde{t}})}^2 &= \int_{\Omega} \left\{ \int_0^{\tilde{t}} |u([\gamma_j(u)](t, x), x)|^2 dt \right\} dx \\ &\leq \frac{1}{c_0} \int_{\Omega} \left\{ \int_0^{\tilde{t}} |u(\psi_j(t, x), x)|^2 \frac{\partial \psi_j}{\partial t}(t, x) dt \right\} dx \\ &\leq \frac{1}{c_0} \| u \|_{L^2(Q_{\tilde{t}})}^2, \quad j = 0, 1 \quad 0 < \tilde{t} \leq T, \quad (2.8) \end{aligned}$$

and thus we obtain (A_2) from (B_2) . Similarly,

$$\| Du([\gamma_2(u)](t, x), x) \|_{L^2(Q_{\tilde{t}})}^2 \leq \frac{1}{c_0} \| Du \|_{L^2(Q_{\tilde{t}})}^2.$$

Inequality (2.8) implies

$$[g_2(u([\gamma_0(u)](t, x), x))](t) \geq \text{const} [1 + \| u \|_{L^2(Q_{\tilde{t}})}]^{-\sigma^*} \quad (2.9)$$

and by (B_4)

$$\begin{aligned} \int_{Q_t} [h_2^1(u([\gamma_1(u)](t, x), x))]^{q_1^1}(\tau, x) d\tau dx &\leq \text{const} [1 + \|u\|_{L^2(Q_t)}]^\sigma, \quad (2.10) \\ \int_{Q_t} [h_2^2(Du([\gamma_2(u)](t, x), x))]^{q_1^2}(\tau, x) d\tau dx &\leq \text{const} [1 + \|Du\|_{L^2(Q_t)}]^\sigma. \end{aligned}$$

Hence, by using the notations

$$\begin{aligned} v^1(t, x) &= u([\gamma_1(u)](t, x), x), \\ v^2(t, x) &= Du([\gamma_2(u)](t, x), x), \\ |a_0^j(t, x, \zeta_0, \zeta; v^j)\zeta_0| &\leq [h_2^j(v^j)](t, x) \text{const} [1 + |\zeta_0|^{\tilde{\rho}_j+1} + |\zeta|^{\tilde{\rho}_j+1}] \quad (2.11) \\ &\leq \varepsilon [g_2(v^j)](t) (|\zeta_0|^p + |\zeta|^p) + C(\varepsilon) \left\{ [h_2^j(v^j)](t, x)^{q_1^j} + 1 \right\}, \quad j = 1, 2 \end{aligned}$$

where $q_1^j = p_1^j / (p_1^j - 1)$, $p_1^j = p / (\tilde{\rho}_j + 1)$. Choosing sufficiently small $\varepsilon > 0$, one obtains (A_4) for functions \tilde{a}_i from (B_4) and (2.10) with

$$\begin{aligned} [k_2(u)](t, x) &= C(\varepsilon) \left\{ [h_2^1(u[\gamma_1(u)](t, x), x)]^{q_1^1}(t, x) + 1 \right\} \\ &\quad + C(\varepsilon) [h_2^2(Du[\gamma_2(u)](t, x), x)]^{q_1^2}(t, x). \end{aligned}$$

Finally, we show that functions \tilde{a}_i satisfy (A_5) . Assume that $(u_k) \rightarrow u$ weakly in $L^p(0, T; V)$, $(D_t u_k) \rightarrow D_t u$ weakly in $L^q(0, T; V^*)$, $(\zeta_0^k) \rightarrow \zeta_0$ in \mathbb{R} , $(\zeta^k) \rightarrow \zeta$ in \mathbb{R}^n . Then $(u_k) \rightarrow u$ strongly in $L^2(Q_T)$, for a subsequence and for $j = 0, 1$

$$\begin{aligned} u_k([\gamma_j(u_k)](t, x), x) - u([\gamma_j(u)](t, x), x) &= \{u_k([\gamma_j(u_k)](t, x), x) - u([\gamma_j(u_k)](t, x), x)\} \\ &\quad + \{u([\gamma_j(u_k)](t, x), x) - u([\gamma_j(u)](t, x), x)\}. \quad (2.12) \end{aligned}$$

For the first term in the right hand side of (2.12) we have (by using the notation $\psi_j^k(t, x) = [\gamma_j(u_k)](t, x)$, (G))

$$\begin{aligned} &\int_{\Omega} \left\{ \int_0^T |u_k([\gamma_j(u_k)](t, x), x) - u([\gamma_j(u_k)](t, x), x)|^2 dt \right\} dx \\ &\leq \frac{1}{c_0} \int_{\Omega} \left\{ \int_0^T |u_k(\psi_k(t, x), x) - u(\psi_k(t, x), x)|^2 \frac{\partial \psi_k}{\partial t} dt \right\} dx \\ &\leq \frac{1}{c_0} \int_{Q_T} |u_k(\tau, x) - u(\tau, x)|^2 d\tau dx \rightarrow 0. \end{aligned}$$

Further, $u \in L^p(0, T; V)$, $D_t u \in L^q(0, T; V^*)$ imply $u \in C([0, T]; L^2(\Omega))$ (see, e.g. [11]). Thus $u : [0, T] \rightarrow L^2(\Omega)$ is uniformly continuous, hence for arbitrary $\varepsilon > 0$ there exists $\delta > 0$ such that

$$\int_{\Omega} |u([\gamma_j(u_k)](t, x), x) - u([\gamma_j(u)](t, x), x)|^2 dx < \varepsilon$$

if $|[\gamma_j(u_k)](t, x) - [\gamma_j(u)](t, x)| < \delta$ for all $(t, x) \in Q_T$.

Since the operator $\gamma_j : L^2(Q_T) \rightarrow C(\overline{Q_T})$ is continuous, there exists k_0 such that

$$|[\gamma_j(u_k)](t, x) - [\gamma_j(u)](t, x)| < \delta \text{ for } k \geq k_0.$$

Consequently, for $k \geq k_0$

$$\int_{Q_T} |u([\gamma_j(u_k)](t, x), x) - u([\gamma_j(u)](t, x), x)|^2 dx dt < \varepsilon T,$$

i.e the second term on the right hand side of (2.12) is converging to 0 in $L^2(Q_T)$.

Thus we have for the functions

$$v_k^j(t, x) = u_k([\gamma_j(u_k)](t, x), x), \quad v^j(t, x) = u([\gamma_j(u)](t, x), x), \quad j = 0, 1$$

that $(v_k^j) \rightarrow v^j$ strongly in $L^2(Q_T)$. Similarly, by using assumption (G) and the substitution in (2.8), for

$$v_k^2(t, x) = D_l u_k([\gamma_2(u_k)](t, x), x), \quad v^2(t, x) = D_l u([\gamma_2(u)](t, x), x) \quad (l = 1, \dots, n)$$

we have $(v_k^2) \rightarrow v^2$ strongly in $L^2(Q_T)$, assuming that $(D_l u_k) \rightarrow D_l u$ in $L^2(Q_T)$.

So by (B_5) assumption (A_5) is satisfied for \tilde{a}_i ($i = 0, 1, \dots, n$). Therefore, by Theorem 2.1 we obtain the existence of solutions to (2.7). \square

Now we formulate an existence theorem in $(0, \infty)$ which can be obtained from Theorem 2.2, by using a diagonal process and the Volterra property (see, e.g. [7]). Denote by $L_{loc}^p(0, \infty; V)$ the set of functions $u : (0, \infty) \rightarrow V$ such that for each fixed finite $T > 0$, $u|_{(0, T)} \in L^p(0, T; V)$ and let $Q_\infty = (0, \infty) \times \Omega$, $L_{loc}^\alpha(Q_\infty)$ the set of functions $u : Q_\infty \rightarrow \mathbb{R}$ such that $u|_{Q_T} \in L^\alpha(Q_T)$ for any finite T . On operators γ_j assume

(G_∞) Operators $\gamma_j : L_{loc}^2(Q_\infty) \rightarrow C(\overline{Q_\infty})$ are of Volterra type, i.e. $\gamma_j(u)|_{Q_T}$ depends only on $u|_{Q_T}$, for any finite T and $\gamma_j, \frac{\partial}{\partial t}[\gamma_2(\cdot)] : L^2(Q_T) \rightarrow C(\overline{Q_T})$ are continuous for every T . Further, $[\gamma_j(u)](\cdot, x)$ is absolutely continuous for a.e. fixed $x \in \Omega$,

$$\frac{\partial}{\partial t}[\gamma_j(u)](t, x) \geq c_0, \quad 0 \leq [\gamma_j(u)](t, x) \leq t$$

with some constant $c_0 > 0$.

Theorem 2.3. *Assume that*

$$a_i, a_0^j : Q_\infty \times \mathbb{R}^{n+1} \times L_{loc}^2(Q_\infty) \rightarrow \mathbb{R}, \quad \gamma_j : L_{loc}^p(Q_\infty) \rightarrow C(\overline{Q_\infty})$$

satisfy assumptions (G_∞) and (B_1) – (B_5) for any finite T , further, $a_i(t, x, \zeta_0, \zeta; u)|_{Q_T}$, $a_0^j(t, x, \zeta_0, \zeta; u)|_{Q_T}$ depend only on $u|_{Q_T}$ (Volterra property). Then for any $f \in L_{loc}^q(0, \infty; V^)$, $u_0 \in L^2(\Omega)$ there exists $u \in L_{loc}^p(0, \infty; V)$ which is a solution of (2.7) for any finite T .*

3. Boundedness and stabilization

Theorem 3.1. *Let the assumptions of Theorem 2.3 be satisfied such that $\gamma_0(u)$ is depending only on t (not on x) and for all $u \in L^2_{loc}(Q_\infty)$, sufficiently large t we have on operators g_2, h_2^j (in (B_4))*

$$[g_2(u)](t) \geq \text{const} \left[1 + \sup_{\tau \in [0, t]} \int_{\Omega} u^2(\tau, x) dx \right]^{-\sigma^*/2}, \quad t \in (0, \infty), \quad (3.1)$$

$$\int_{\Omega} [h_2^1(u)](t, x)^{q_1} dx \leq \text{const} \left[1 + \left(\int_{\Omega} u^2(t, x) dx \right)^{\tilde{\sigma}/2} \right], \quad (3.2)$$

where $0 < \tilde{\sigma} < p - \sigma^*$, $\tilde{\sigma} \leq 2$. In the particular case when $\gamma_1(u)$ is depending only on t and not on x , we assume (instead of (3.2))

$$\begin{aligned} & \int_{\Omega} [h_2^1(u)](t, x)^{q_1} dx \\ & \leq \text{const} \left[1 + \sup_{\tau \in [0, t]} \left(\int_{\Omega} u^2(t, x) dx \right)^{\sigma/2} + \varphi(t) \left(\sup_{\tau \in [0, t]} \int_{\Omega} u^2(t, x) dx \right)^{(p-\sigma^*)/2} \right] \end{aligned} \quad (3.3)$$

where $\lim_{\infty} \varphi = 0$. Further, for all $u \in L^p(0, \infty; V)$

$$|h_2^2(u)| \leq \text{const}. \quad (3.4)$$

Finally, $\|f(t)\|_{V^*}$ is bounded for $t \in (0, \infty)$.

Then for a solution $u \in L^p_{loc}(0, \infty; V)$ of (2.7) in $(0, \infty)$, $\int_{\Omega} u^2(t, x) dx$ is bounded for $t \in (0, \infty)$.

Proof. Let $u \in L^p_{loc}(0, \infty; V)$ be a solution of (2.7). Applying (2.7) to $u(t) \in V$, we obtain for

$$\begin{aligned} \tilde{y}(t) &= \int_{\Omega} u^2(t, x) dx, \quad y_0(t) = \int_{\Omega} u^2([\gamma_0(u)](t), x) dx, \\ y_1(t) &= \int_{\Omega} u^2([\gamma_1(u)](t, x), x) dx, \end{aligned}$$

by using (2.11) with sufficiently small $\varepsilon > 0$,

$$\begin{aligned} & \frac{1}{2} \tilde{y}'(t) + \frac{1}{2} g_2(u([\gamma_0(u)](t), x))(t) \|u(t)\|_V^p \\ & - C \left\{ \int_{\Omega} [h_2^1(u([\gamma_1(u)](t), x))]^{q_1} dx + \int_{\Omega} [h_2^2(Du([\gamma_2(u)](t), x))]^{q_2} dx + 1 \right\} \\ & \leq \|f(t)\|_{V^*} \|u(t)\|_V \\ & \leq \text{const} \|u(t)\|_V. \end{aligned} \quad (3.5)$$

Young's inequality implies

$$\begin{aligned} \|u(t)\|_V &\leq \frac{\varepsilon^p}{p} g_2(u([\gamma_0(u)](t), x))(t) \|u(t)\|_V^p \\ &\quad + \frac{1}{q\varepsilon^q} \frac{1}{g_2(u([\gamma_0(u)](t), x))^{q/p}}. \end{aligned} \quad (3.6)$$

Choosing sufficiently small $\varepsilon > 0$, by

$$\|u(t)\|_V^p \geq \text{const} \tilde{y}(t)^{p/2}$$

we obtain in the case (3.3), when $\gamma_1(u)$ is not depending on x ,

$$\begin{aligned} &\tilde{y}'(t) + c^* \tilde{y}(t)^{p/2} \left[1 + \sup_{\tau \in [0, t]} y_0(\tau) \right]^{-\sigma^*/2} \\ &\leq \text{const} \left[1 + \sup_{\tau \in [0, t]} y_1(\tau)^{\sigma/2} + \varphi(t) \sup_{\tau \in [0, t]} y_1(\tau)^{(p-\sigma^*)/2} + \sup_{\tau \in [0, t]} y_1(\tau)^{(q/p)(\sigma^*/2)} \right]. \end{aligned}$$

Since $[\gamma_j(u)](\tau) \leq \tau$, $\sup_{\tau \in [0, t]} y_j(\tau) \leq \sup_{\tau \in [0, t]} \tilde{y}(\tau)$ ($j = 0, 1$), thus we have

$$\begin{aligned} &\tilde{y}'(t) + c^* \tilde{y}(t)^{p/2} \left[1 + \sup_{\tau \in [0, t]} \tilde{y}(\tau) \right]^{-\sigma^*/2} \\ &\leq \text{const} \left[1 + \sup_{\tau \in [0, t]} \tilde{y}(\tau)^{\sigma/2} + \varphi(t) \sup_{\tau \in [0, t]} \tilde{y}(\tau)^{(p-\sigma^*)/2} + \sup_{\tau \in [0, t]} \tilde{y}(\tau)^{(q/p)(\sigma^*/2)} \right]. \end{aligned}$$

Since $\sigma < p - \sigma^*$, $\lim_{\infty} \varphi = 0$ and $(q/p)\sigma^* < p - \sigma^*$, one obtains (as in [8]) that the above inequality implies the boundedness of $\tilde{y}(t)$.

In the case (3.2) (when $\gamma_1(u)$ may depend on t, x),

$$\int_{\Omega} |h_2^1(u([\gamma_1(u)](t, x), x))|^{q_1^1} dx \leq \text{const} \left[1 + \left(\int_{\Omega} |u([\gamma_1(u)](t, x), x)|^2 dx \right)^{\tilde{\sigma}/2} \right].$$

Hence, by using the notation $\psi(t, x) = [\gamma_1(u)](t, x)$

$$\begin{aligned} &\int_{T_1}^{T_2} \left\{ \int_{\Omega} |h_2^1(u([\gamma_1(u)](t, x), x))|^{q_1^1} dx \right\} \\ &\leq \text{const}(T_2 - T_1) + \text{const} \int_{T_1}^{T_2} \left[\int_{\Omega} |u([\gamma_1(u)](t, x), x)|^2 dx \right]^{\tilde{\sigma}/2} dt \\ &\leq \text{const}(T_2 - T_1) + \text{const} \left\{ \int_{\psi(T_1, x)}^{\psi(T_2, x)} \left[\int_{\Omega} |u(\tau, x)|^2 dx \right]^{\tilde{\sigma}/2} d\tau \right\}. \end{aligned}$$

Thus from (3.5), (3.6) one obtains

$$\begin{aligned} & \tilde{y}(T_2) - \tilde{y}(T_1) + \tilde{c}^* \int_{T_1}^{T_2} \tilde{y}(t)^{p/2} \left[1 + \sup_{\tau \in [0, t]} \tilde{y}(\tau) \right]^{-\sigma^*/2} dt \\ & \leq \text{const}(T_2 - T_1) + \text{const} \left\{ \int_{\Omega} \left[\int_{\psi(T_1, x)}^{\psi(T_2, x)} |u(\tau, x)|^2 d\tau \right] dx \right\}^{\tilde{\sigma}/2} \\ & \leq \text{const}(T_2 - T_1) + \text{const} \left[\int_{d_1 T_1}^{d_2 T_2} \tilde{y}(\tau) d\tau \right]^{\tilde{\sigma}/2} \end{aligned}$$

with some constants $d_1, d_2 > 0$. Since $\tilde{\sigma} < p - \sigma^*$, the last inequality implies (as above) the boundedness of \tilde{y} . \square

Now we formulate a theorem on stabilization of $u(t)$ as $t \rightarrow \infty$.

Theorem 3.2. *Assume that the conditions of Theorem 3.1 are fulfilled with Volterra operators*

$$g_1 : L_{loc}^2(Q_\infty) \rightarrow \mathbb{R}^+, \quad (3.7)$$

$$k_1 : L_{loc}^2(Q_\infty) \rightarrow L^q(\Omega) \quad (3.8)$$

such that $a_0^1(t, x, \zeta_0, \zeta; 0) = 0$ and the following monotonicity condition is satisfied with some constant $c_2 > 0$:

$$\begin{aligned} & \sum_{i=1}^n [a_i(t, x, \zeta_0, \zeta; u) - a_i(t, x, \zeta_0^*, \zeta^*; u)] (\zeta_i - \zeta_i^*) \\ & + [a_0^0(t, x, \zeta_0, \zeta; u) - a_0^0(t, x, \zeta_0^*, \zeta^*; u)] (\zeta_0 - \zeta_0^*) \\ & \geq [g_2(u)](t) [|\zeta - \zeta^*|^p + |\zeta_0 - \zeta_0^*|^p] + c_2 (\zeta_0 - \zeta_0^*)^2. \end{aligned} \quad (3.9)$$

Further, for arbitrary fixed $u \in L_{loc}^p(0, \infty; V) \cap L^\infty(0, \infty; L^2(\Omega))$, with $D_t u \in L_{loc}^q(0, \infty; V^*)$, $(\zeta_0, \zeta) \in \mathbb{R}^{n+1}$, a.a. $x \in \Omega$

$$\begin{aligned} |a_i(t, x, \zeta_0, \zeta; u) - a_{i, \infty}(x, \zeta_0, \zeta)| & \leq \Phi(t) [1 + |\zeta_0|^{p-1} + |\zeta|^{p-1}], \quad i = 1, \dots, n, \\ |a_0^0(t, x, \zeta_0, \zeta; u) - a_{0, \infty}^0(x, \zeta_0, \zeta)| & \leq \Phi(t) [1 + |\zeta_0|^{p-1} + |\zeta|^{p-1}], \\ |a_0^2(t, x, \zeta_0, \zeta; u)| & \leq \Psi(t) [1 + |\zeta_0|] \end{aligned} \quad (3.10)$$

with some Carathéodory functions $a_{i, \infty}, a_{0, \infty}^0$ where $\int_0^\infty \Phi(t)^q dt < \infty$, $\int_0^\infty \Psi(t)^2 dt < \infty$. On a_0^1 we assume for every $w \in V$ the inequality

$$|a_0^1(t, x, \zeta_0, \zeta; w) - a_{0, \infty}^1(x; w)| \leq \Psi(t) [1 + |\zeta_0|]$$

where $a_{0, \infty}^1 : \Omega \times V \rightarrow \mathbb{R}$ is such that $a_{0, \infty}^1(\cdot; w)$ is measurable; there exist constants $a > 0, 0 < c_3 < c_2$ such that for all $u, u^*, v \in L_{loc}^p(0, \infty; V) \cap L^\infty(0, \infty; L^2(\Omega))$,

$T_1 > T_2 \geq 0$,

$$\begin{aligned} \int_{T_1}^{T_2} \int_{\Omega} |a_0^1(t, x, v, Dv; u) - a_0^1(t, x, v, Dv; u^*)|^2 dt dx & \quad (3.11) \\ & \leq c_0 c_3^2 \int_{\max\{0, T_1 - a\}}^{T_2} \int_{\Omega} [u - u^*]^2 dt dx, \quad [\gamma_1(u)](t, x) \geq t - a. \end{aligned}$$

Finally, there exists $f_{\infty} \in V^*$ such that

$$\|f(t) - f_{\infty}\|_{V^*} \leq \Phi(t). \quad (3.12)$$

Then for a solution of (2.4) in $(0, \infty)$ we have

$$\int_0^{\infty} \|u(t) - u_{\infty}\|_V^p dt < \infty, \quad \int_0^{\infty} \|u(t) - u_{\infty}\|_{L^2(\Omega)}^2 dt < \infty, \quad (3.13)$$

$$\lim_{t \rightarrow \infty} \|u(t) - u_{\infty}\|_{L^2(\Omega)} = 0, \quad (3.14)$$

$$\begin{aligned} \int_T^{\infty} \|u(t) - u_{\infty}\|_{L^2(\Omega)}^2 dt & \leq \text{const} \left\{ e^{-\tilde{\gamma}T} \right. \\ & \left. + \int_0^T \left[e^{-\tilde{\gamma}(T-t)} \int_t^{\infty} (\Phi(\tau)^q + \Psi(\tau)^2) d\tau \right] dt \right\} \end{aligned} \quad (3.15)$$

with some constant $\tilde{\gamma} > 0$ where $u_{\infty} \in V$ is the unique solution to

$$A_{\infty}(u_{\infty}) = f_{\infty} \quad (3.16)$$

and the operator $A_{\infty} : V \rightarrow V^*$ is defined for $z, v \in V$ by

$$\langle A_{\infty}(z), v \rangle = \sum_{i=1}^n \int_{\Omega} a_{i,\infty}(x, z, Dz) D_i v dx + \int_{\Omega} a_{0,\infty}^0(x, z, Dz) v dx + \int_{\Omega} a_{0,\infty}^1(x; z) v dx.$$

Proof. Since the functions $a_{i,\infty}$ and $a_{0,\infty}^0$ satisfy the Carathéodory condition and $a_{0,\infty}^1(\cdot; z)$ is measurable, we obtain from (B_2) , (3.10) that $A_{\infty} : V \rightarrow V^*$ is bounded and demicontinuous. From (3.9), (3.10), (3.11) it is not difficult to derive that A_{∞} is strictly monotone and by (B_4) A_{∞} is coercive. Thus there exists a unique solution of (3.16).

If u is a solution of (2.4) in $(0, \infty)$ then by (3.16) one obtains

$$\begin{aligned} \langle D_t[u(t) - u_{\infty}], u(t) - u_{\infty} \rangle + \langle [A(u)](t) - A_{\infty}(u_{\infty}), u(t) - u_{\infty} \rangle = & \quad (3.17) \\ \langle f(t) - f_{\infty}, u(t) - u_{\infty} \rangle. \end{aligned}$$

By using the notation

$$\begin{aligned}
 \langle [A_u(u_\infty)](t), z \rangle &= \int_{\Omega} \sum_{i=1}^n a_i(t, x, u_\infty(x), Du_\infty(x); u([\gamma_0(u)](t, x), x)) D_i z \, dx \\
 &\quad + \int_{\Omega} a_0^0(t, x, u_\infty(x), Du_\infty(x); u([\gamma_0(u)](t, x), x)) z \, dx \\
 &\quad + \int_{\Omega} a_0^1(t, x, u, Du; u_\infty) z \, dx \\
 &\quad + \int_{\Omega} a_0^2(t, x, u, Du; Du([\gamma_2(u)](t, x), x)) z \, dx,
 \end{aligned}$$

(3.9) and Young's inequality, we obtain for the second term in (3.17)

$$\begin{aligned}
 &\langle [A(u)](t) - A_\infty(u_\infty), u(t) - u_\infty \rangle \tag{3.18} \\
 &= \langle [A(u)](t) - [A_u(u_\infty)](t), u(t) - u_\infty \rangle + \langle [A_u(u_\infty)](t) - A_\infty(u_\infty), u(t) - u_\infty \rangle \\
 &\geq [g_2(u([\gamma_0(u)](t, x), x))](t) \| u(t) - u_\infty \|_V^p + c_2 \int_{\Omega} |u(t) - u_\infty|^2 \, dx \\
 &\quad - \left| \int_{\Omega} [a_0^1(t, x, u, Du; u([\gamma_1(u)](t, x), x)) - a_0^1(t, x, u, Du; u_\infty)] [u(t) - u_\infty] \, dx \right| \\
 &\quad - |\langle [A_u(u_\infty)](t) - A_\infty(u_\infty), u(t) - u_\infty \rangle|.
 \end{aligned}$$

For arbitrary $\varepsilon > 0$

$$\begin{aligned}
 &|\langle [A_u(u_\infty)](t) - A_\infty(u_\infty), u(t) - u_\infty \rangle| \\
 &\leq \frac{\varepsilon^p}{p} \| u(t) - u_\infty \|_V^p + \frac{\varepsilon^2}{2} \| u(t) - u_\infty \|_{L^2(\Omega)}^2 \\
 &\quad + C(\varepsilon) \sum_{i=1}^n \int_{\Omega} |a_i(t, x, u_\infty, Du_\infty; u([\gamma_0(u)](t, x), x)) - a_{i,\infty}(x, u_\infty, Du_\infty)|^q \, dx \\
 &\quad + C(\varepsilon) \int_{\Omega} |a_0^0(t, x, u_\infty, Du_\infty; u([\gamma_0(u)](t, x), x)) - a_{0,\infty}^0(x, u_\infty, Du_\infty)|^q \, dx \\
 &\quad + C(\varepsilon) \int_{\Omega} |a_0^1(t, x, u, Du; u_\infty) - a_{0,\infty}^1(x; u_\infty)|^2 \, dx \\
 &\quad + C(\varepsilon) \int_{\Omega} |a_0^2(t, x, u, Du; Du([\gamma_2(u)](t, x), x))|^2 \, dx
 \end{aligned}$$

and

$$|\langle f(t) - f_\infty, u(t) - u_\infty \rangle| \leq \varepsilon^p/p \| u(t) - u_\infty \|_V^p + C(\varepsilon) \| f(t) - f_\infty \|_{V^*}^q.$$

Thus, since $\int_{\Omega} u^2(t) \, dx$ is bounded and

$$\langle D_t[u(t) - u_\infty], u(t) - u_\infty \rangle = \frac{1}{2} y'(t) \text{ where } y(t) = \int_{\Omega} |u(t) - u_\infty|^2 \, dx,$$

integrating (3.17) over (T_1, T_2) , we obtain with sufficiently small ε

$$\begin{aligned} y(T_2) - y(T_1) + c^* \int_{T_1}^{T_2} \|u(t) - u_\infty\|_V^p dt + \tilde{c}_2 \int_{T_1}^{T_2} y(t) dt \\ - \left[\int_{T_1}^{T_2} \int_{\Omega} |a_0^1(t, x, u, Du; u([\gamma_1(u)](t, x), x)) - a_0^1(t, x, u, Du; u_\infty)|^2 dt dx \right]^{1/2} \\ \times \left[\int_{T_1}^{T_2} y dt \right]^{1/2} \leq c \left(\int_{T_1}^{T_2} \Phi^q dt + \int_{T_1}^{T_2} \Psi^2 dt \right) \end{aligned} \quad (3.19)$$

with some constants $c^*, c, \tilde{c}_2 > 0$ where $c_3 < \tilde{c}_2 < c_2$. By (3.11) for sufficiently large T_1

$$\begin{aligned} \int_{T_1}^{T_2} \int_{\Omega} |a_0^1(t, x, u, Du; u([\gamma_1(u)](t, x), x)) - a_0^1(t, x, u, Du; u_\infty)|^2 dt dx \\ \leq c_0 c_3^2 \int_{\max\{0, T_1 - a\}}^{T_2} \left[\int_{\Omega} |u([\gamma_1(u)](t, x), x) - u_\infty(x)|^2 dx \right] dt \\ \leq c_3^2 \int_{\max\{0, T_1 - 2a\}}^{T_2} \left[\int_{\Omega} |u(\tau, x) - u_\infty(x)|^2 dx \right] d\tau. \end{aligned}$$

Since y is bounded, $c_3 < \tilde{c}_2$ and $\int_0^\infty \Phi^q dt < \infty$, $\int_0^\infty \Psi^2 dt < \infty$, we obtain from (3.19) with $T_1 = 0$ (3.13).

Thus by (3.11), (3.19)

$$\int_0^\infty \int_{\Omega} |a_0^1(t, x, u, Du; u([\gamma_1(u)](t, x), x)) - a_0^1(t, x, u, Du; u_\infty)|^2 dt dx < \infty,$$

and, consequently, $\lim_\infty y = 0$.

Because, first observe that by (3.13)

$$\liminf_{t \rightarrow \infty} y(t) = 0$$

Hence there exist

$$T_1 < T_2 < \dots < T_k < \dots \rightarrow +\infty \text{ such that } \lim_{k \rightarrow \infty} y(T_k) = 0.$$

Applying (3.19) to $T_1 = T_k$ and $T_2 = T$ with $T > T_k$, we obtain

$$0 \leq y(T) \leq y(T_k) + a_k \quad \text{where } \lim_{k \rightarrow \infty} a_k = 0$$

and so $\lim_\infty y = 0$.

Finally, from (3.11), (3.14), (3.19) we obtain as $T_2 \rightarrow \infty$

$$\begin{aligned} -y(T_1) + c^* \int_{T_1}^\infty \|u(t) - u_\infty\|_V^p dt + \tilde{c}_2 \int_{T_1}^\infty y dt \\ - c_3 \left[\int_{T_1 - 2a}^\infty y dt \right]^{1/2} \left[\int_{T_1}^\infty y dt \right]^{1/2} \leq \text{const} \left[\int_{T_1}^\infty \Phi(t)^q dt + \int_{T_1}^\infty \Psi(t)^2 dt \right]. \end{aligned}$$

Hence, by using the notation $Y(T) = \int_T^\infty y(t)dt$,

$$\begin{aligned} Y'(T_1) + (\tilde{c}_2 - c_3/2)Y(T_1) - (c_3/2)Y(T_1 - 2a) \\ \leq Y'(T_1) + \tilde{c}_2Y(T_1) - c_3Y(T_1 - 2a)^{1/2}Y(T_1)^{1/2} \\ \leq \text{const} \left[\int_{T_1}^\infty \Phi^q dt + \int_{T_1}^\infty \Psi^2 dt \right]. \end{aligned} \tag{3.20}$$

Since the real part of the roots of the characteristic equation

$$\lambda + (\tilde{c}_2 - c_3/2) - (c_3/2)e^{-2\lambda a} = 0$$

is negative, we obtain for the solution the inequality (3.15). □

Example 3.1. Consider examples of the following type:

$$\begin{aligned} a_i(t, x, \zeta_0, \zeta; u) &= b(t, x, [H(u)](t, x))\zeta_i|\zeta|^{p-2}, \quad i = 1, \dots, n, \\ a_0^0(t, x, \zeta_0, \zeta; u) &= b_0(t, x, [H_0(u)](t, x))\zeta_0|\zeta_0|^{p-2} + c_2\zeta_0, \quad c_2 \geq 0 \end{aligned}$$

where b, b_0 are bounded Carathéodory functions satisfying with some positive constant c_3

$$b(t, x, \theta) \geq \frac{c_3}{1 + |\theta|^{\sigma^*}}, \quad b_0(t, x, \theta) \geq \frac{c_3}{1 + |\theta|^{\sigma^*}};$$

$$a_0^j(t, x, \zeta_0, \zeta; u) = b_0^j(t, x, [F_j(u)](t, x))\alpha_0^j(t, x, \zeta_0, \zeta), \quad j = 1, 2 \tag{3.21}$$

(or a_0^j is a sum of such products), where functions α_0^j, b_0^j satisfy

$$|\alpha_0^j(t, x, \zeta_0, \zeta)| \leq \text{const}[1 + |\zeta_0|^{\tilde{p}^j} + |\zeta|^{\tilde{p}^j}], \quad |b_0^j(t, x, \theta)|^{q_1^j} \leq \text{const}(1 + |\theta|^2).$$

Finally,

$$H, H_0 : L^2(Q_T) \rightarrow C(\overline{Q_T}), \quad F_j : L^2(Q_T) \rightarrow L^2(Q_T)$$

are continuous operators of Volterra type, satisfying

$$\| H(u) \|_{C(\overline{Q_t})} \leq \text{const} \| u \|_{L^2(Q_t)}, \quad \| H_0(u) \|_{C(\overline{Q_t})} \leq \text{const} \| u \|_{L^2(Q_t)},$$

$$\int_{Q_t} |F_j(u)|^2 \leq \text{const} \left(\int_{Q_t} |u|^2 \right)^{\sigma/2}, \quad t > 0.$$

It is not difficult to show that the conditions of the existence Theorem 2.2 are fulfilled. If the above conditions hold for all $T > 0$ and $t > 0$ then the conditions of Theorem 2.3 are satisfied.

Further, assumptions of Theorem 3.1 are fulfilled if the following additional assumptions are satisfied. Assumption (3.1) is satisfied if

$$\begin{aligned} \| H(u) \|_{C(\overline{Q_t})} &\leq \text{const} \sup_{\tau \in [0, t]} \left[\int_{\Omega} u^2(\tau, x) dx \right]^{1/2}, \\ \| H_0(u) \|_{C(\overline{Q_t})} &\leq \text{const} \sup_{\tau \in [0, t]} \left[\int_{\Omega} u^2(\tau, x) dx \right]^{1/2} \quad t > 0, \end{aligned}$$

(3.2) is satisfied if

$$\int_{\Omega} [F_1(u)]^2(t, x) dx \leq \text{const} \left(\int_{\Omega} u^2(t, x) dx \right)^{\tilde{\sigma}/2} \quad \text{for all } t > 0,$$

(3.3) is satisfied if for all $t > 0$

$$\begin{aligned} \int_{\Omega} |F_1(u)|^2(t, x) dx &\leq \text{const} \left\{ 1 + \left[\sup_{\tau \in [0, t]} \int_{\Omega} u^2(t, x) dx \right]^{\sigma/2} \right\} \\ &+ \varphi(t) \left[\sup_{\tau \in [0, t]} \int_{\Omega} u^2(t, x) dx \right]^{(p-\sigma^*)/2}. \end{aligned}$$

Inequality (3.4) is satisfied if

$$|b_0^2(t, x, \theta)| \leq \text{const}.$$

Finally, the assumptions of Theorem 3.2 are fulfilled if the following additional conditions are satisfied for our example. $c_2 > 0$, there exist measurable functions $b_{\infty}, b_{0, \infty}$ such that for all fixed $u \in L_{loc}^p(0, \infty; V) \cap L^{\infty}(0, \infty; L^2(\Omega))$, with $D_t u \in L_{loc}^q(0, \infty; V^*)$

$$\begin{aligned} |b(t, x, [H(u)](t, x)) - b_{\infty}(x)| &\leq \Phi(t), \quad |b_0(t, x, [H(u)](t, x)) - b_{0, \infty}(x)| \leq \Phi(t), \\ |b_0^2(t, x, \theta)| &\leq \Phi(t). \end{aligned}$$

Functions b, b_0 may have the form

$$b(t, x, \theta) = \frac{b_{\infty}(x)}{1 + \Phi(t)|\theta|^{\sigma^*}}, \quad b_0(t, x, \theta) = \frac{b_{0, \infty}(x)}{1 + \Phi(t)|\theta|^{\sigma^*}}$$

where $b_{\infty}, b_{0, \infty}$ are measurable functions having values between two positive constants. Further,

$$a_0^1(t, x, \zeta_0, \zeta; u) = b_{0, \infty}^1(x, F_1(u)) + \beta(t, \zeta_0, \zeta), \quad (3.22)$$

where

$$|\beta(t, \zeta_0, \zeta)| \leq \Psi(t)(1 + |\zeta_0|),$$

the Carathéodory function $b_{0, \infty}^1$ satisfies the Lipschitz condition

$$|b_{0, \infty}^1(x, \theta) - b_{0, \infty}^1(x, \theta^*)| \leq \tilde{c}_3 |\theta - \theta^*|$$

and the operator F_1 satisfies

$$\int_{T_1}^{T_2} \int_{\Omega} |F_1(u) - F_1(u^*)|^2 dt dx \leq c_0 \hat{c}_3^2 \int_{\max\{0, T_1 - a\}}^{T_2} \int_{\Omega} |u - u^*|^2 dt dx, \quad c_2 > \tilde{c}_3 \hat{c}_3.$$

(In this case a_0^1 is a sum of two products of the form (3.21).)

A simple example satisfying the conditions of Theorem 3.1 is

$$D_t u - \Delta_p u + |u|^{p-2} u + c_2 u + b_0^1(t, x, u([\gamma_1(u)](t), x)) + b_0^2(t, x, Du([\gamma_2(u)](t), x)) = f$$

where Δ_p is the p -Laplacian, defined by $\Delta_p u = \sum_{j=1}^n D_j(|Du|^{p-2} D_j u)$.

If the fourth term is given by (3.22) and $|b_0^2(t, x, \theta)| \leq \Psi(t)$ then Theorem 3.2 holds.

References

- [1] R. A. Adams, Sobolev spaces. Academic Press, New York - San Francisco - London, 1975.
- [2] J. Berkovits, V. Mustonen, Topological degree for perturbations of linear maximal monotone mappings and applications to a class of parabolic problems. *Rend. Mat. Ser. VII*, 12, Roma (1992), 597–621.
- [3] I. Györi, F. Hartung, On the exponential stability of a nonlinear state-dependent delay system. *Advances in Mathematical Problems in Engineering Aerospace and Sciences*. Cambridge Scientific Publishers Ltd, 2009, 39–48.
- [4] F. Hartung, J. Turi, Stability in a class of functional differential equations with state-dependent delays. *Qualitative Problems for Differential Equations and Control Theory*. World Scientific, 1995, 15–31.
- [5] F. Hartung, T. Krisztin, H.-O. Walther, J. Wu, Functional differential equations with state-dependent delay: theory and applications. *Handbook of Differential Equations: Ordinary Differential Equations*, Vol. 3. Elsevier, North-Holland, 2006, 435–545.
- [6] L. Simon, On different types of nonlinear parabolic functional differential equations. *Pure Math. Appl.* 9 (1998) 181–192.
- [7] L. Simon, On nonlinear hyperbolic functional differential equations. *Math. Nachr.* 217 (2000) 175–186.
- [8] L. Simon, W. Jäger, On non-uniformly parabolic functional differential equations. *Studia Sci. Math. Hungar.* 45 (2008) 285–300.
- [9] L. Simon, Nonlinear functional parabolic equations, *Integral Methods in Science and Engineering*, Vol. 2 Birkhäuser, 2009, 321–326.
- [10] L. Simon: Application of monotone type operators to parabolic and functional parabolic PDE's. *Handbook of Differential Equations. Evolutionary Equations*, Vol. 4, Elsevier, 2008, 267–321.
- [11] E. Zeidler, *Nonlinear functional analysis and its applications II A and II B*. Springer, 1990.